

Approximate traveltimes of waves propagating in laterally varying layered anisotropic media

Ivan Pšenčík¹⁾ and Véronique Farra²⁾

1) Institute of Geophysics, Acad. Sci. Praha, Czech Republic

2) Institut de Physique du Globe, Paris, France

14th IWSA, Perth 2010

Tuesday, April 13, 2010

Outline

Outline

Introduction

Outline

Introduction

First-order common S-wave ray tracing

Outline

Introduction

First-order common S-wave ray tracing

Approximate S-wave traveltime formulae

Outline

Introduction

First-order common S-wave ray tracing

Approximate S-wave traveltime formulae

Transformation of first-order slowness vectors
at an interface (Snell's law)

Outline

Introduction

First-order common S-wave ray tracing

Approximate S-wave traveltime formulae

Transformation of first-order slowness vectors
at an interface (Snell's law)

Numerical examples

Outline

Introduction

First-order common S-wave ray tracing

Approximate S-wave traveltime formulae

Transformation of first-order slowness vectors
at an interface (Snell's law)

Numerical examples

Conclusions

Introduction

traveltimes important in migration and tomography

Introduction

traveltimes important in migration and tomography

standard "anisotropic" ray tracers for S waves

Introduction

traveltimes important in migration and tomography

standard "anisotropic" ray tracers for S waves

- break down in weakly anisotropic media
and in vicinities of singularities

Introduction

traveltimes important in migration and tomography

standard "anisotropic" ray tracers for S waves

- break down in weakly anisotropic media
and in vicinities of singularities
- do not work in isotropic media

Introduction

traveltimes important in migration and tomography

standard "anisotropic" ray tracers for S waves

- break down in weakly anisotropic media
and in vicinities of singularities
- do not work in isotropic media
- generate number of multiple reflections,
which may exceed acceptable limit

Introduction

Solution: use of common S-wave ray concept

(Bakker, 2002; Klimeš, 2006; Farra & Pšenčík, 2008)

Introduction

Solution: use of common S-wave ray concept

(Bakker, 2002; Klimeš, 2006; Farra & Pšenčík, 2008)

- common ray - artificial trajectory approximating rays of S1 and S2 waves

Introduction

Solution: use of common S-wave ray concept

(Bakker, 2002; Klimeš, 2006; Farra & Pšenčík, 2008)

- common ray - artificial trajectory approximating rays of S1 and S2 waves
- traveltimes of S1 and S2 waves evaluated by quadratures along the common ray

Introduction

Solution: use of common S-wave ray concept

(Bakker, 2002; Klimeš, 2006; Farra & Pšenčík, 2008)

- common ray - artificial trajectory approximating rays of S1 and S2 waves
- traveltimes of S1 and S2 waves evaluated by quadratures along the common ray
- at interfaces, slowness vectors of generated waves determined by solving 4th-degree polynomial equation

First-order common S-wave ray tracing

$$dx_i/d\tau = \frac{1}{2}\partial G^{[\mathcal{M}]} / \partial p_i , \quad dp_i/d\tau = -\frac{1}{2}\partial G^{[\mathcal{M}]} / \partial x_i$$

x_i - coordinates of the first-order ray Ω

p_i - components of the first-order slowness vector \mathbf{p}

τ - first-order traveltime

$G^{[\mathcal{M}]}(\mathbf{x}, \mathbf{p})$ - S-wave first-order mean eigenvalue

$$G^{[\mathcal{M}]}(\mathbf{x}, \mathbf{p}) = \frac{1}{2}[G_{S1}^{(1)}(\mathbf{x}, \mathbf{p}) + G_{S2}^{(1)}(\mathbf{x}, \mathbf{p})]$$

$G_{SI}^{(1)}(\mathbf{x}, \mathbf{p})$ - S-wave first-order eigenvalues of Christoffel matrix $\boldsymbol{\Gamma}$

Eikonal equation: $G^{[\mathcal{M}]}(\mathbf{x}, \mathbf{p}) = 1$

Approximate S-wave traveltime formulae

$$\tau_{S1,S2}(\tau, \tau_0) = \tau^{[\mathcal{M}]}(\tau, \tau_0) + \Delta\tau^{[\mathcal{M}]}(\tau, \tau_0) + \Delta\tau_{S1,S2}(\tau, \tau_0)$$

$\tau^{[\mathcal{M}]}(\tau, \tau_0)$ - first-order traveltime between τ_0 and τ on common ray

$\Delta\tau^{[\mathcal{M}]}(\tau, \tau_0)$ - "averaging" correction of first-order traveltime

$$\Delta\tau^{[\mathcal{M}]} = \frac{1}{4} \int_{\tau_0}^{\tau} (B_{13}^2 + B_{23}^2) / (B_{33} - 1) d\tau$$

$\Delta\tau_{S1,S2}(\tau, \tau_0)$ - "separation" traveltime correction

$$\Delta\tau_{S1,S2} = \mp \frac{1}{4} \int_{\tau_0}^{\tau} \sqrt{(M_{11} - M_{22})^2 + 4M_{12}^2} d\tau$$

Approximate S-wave traveltime formulae

$$B_{mn} = B_{mn}(\mathbf{x}, \mathbf{p}) = \Gamma_{ik}(\mathbf{x}, \mathbf{p}) e_i^{[m]}(\mathbf{x}) e_k^{[n]}(\mathbf{x})$$

Γ_{ik} - elements of Christoffel matrix $\boldsymbol{\Gamma}$

$\mathbf{e}^{[m]}$ - triplet of orthonormal vectors

$\mathbf{e}^{[3]} = c^{[\mathcal{M}]} \mathbf{p}, \quad \mathbf{e}^{[1]}, \mathbf{e}^{[2]}$ arbitrarily in the plane $\perp \mathbf{e}^{[3]}$

$c^{[\mathcal{M}]}$ - common S-wave phase velocity

$$M_{MN} = M_{MN}(\mathbf{x}, \mathbf{p}) = B_{MN} - B_{M3} B_{N3} / (B_{33} - 1)$$

Transformation of first-order slowness vectors at an interface (Snell's law)

$$p_i^G = p_i - (p_k N_k) N_i + \xi^G N_i$$

p - first-order common S-wave slowness vector of incident wave

p^G - first-order common S-wave slowness vector of generated wave

N - normal to the interface, $\xi^G = p_k^G N_k$

$$p_i^G - (p_k^G N_k) N_i = p_i - (p_k N_k) N_i \quad - \text{Snell's law}$$

Transformation of first-order slowness vectors at an interface (Snell's law)

$$p_i^G = p_i - (p_k N_k) N_i + \xi N_i$$

$$G^{[\mathcal{M}]}(\mathbf{x}, \mathbf{p}^G) = 1 \quad \text{- eikonal equation}$$

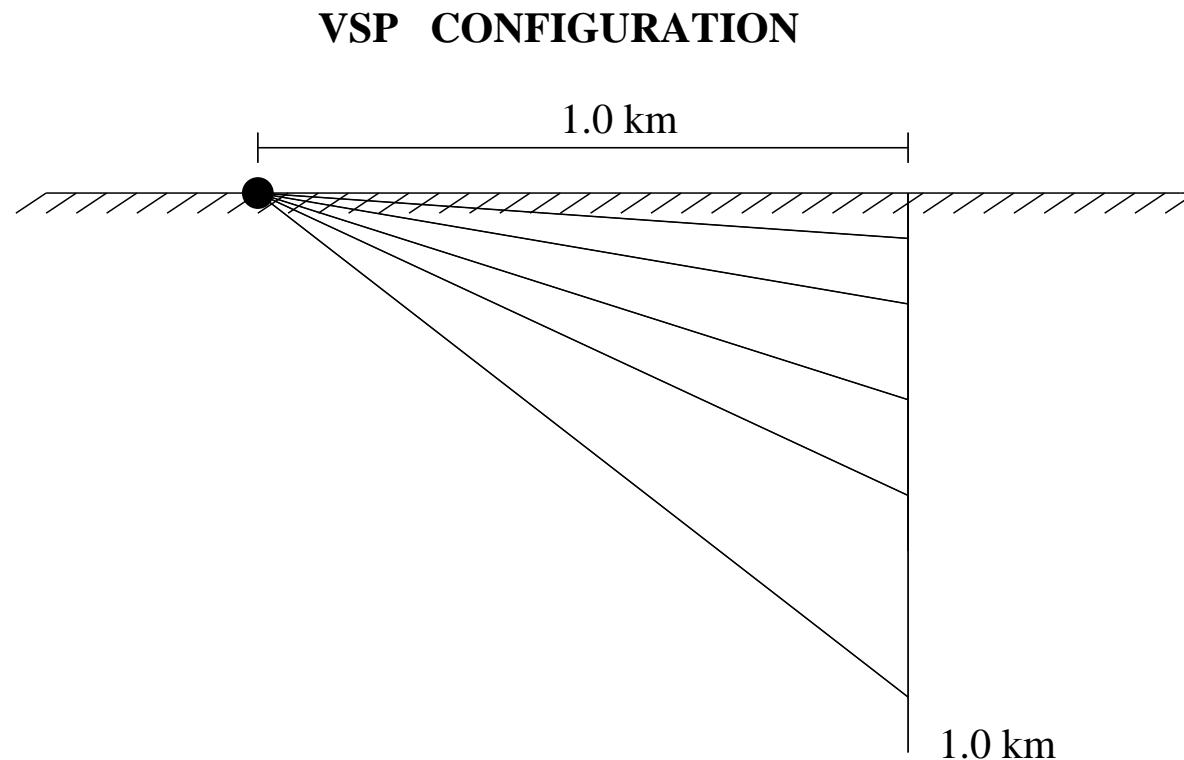
$$G^{[\mathcal{M}]}(\xi) = 1 \quad \text{- polynomial equation of 4th degree for } \xi$$

Iterative solution (Dehghan et al., 2007)

$$\xi^{\{j\}} = \xi^{\{j-1\}} - [G^{[\mathcal{M}]}(p_m^{\{j-1\}}) - 1] / [N_k \frac{\partial G^{[\mathcal{M}]} }{\partial p_k}(p_m^{\{j-1\}})]$$

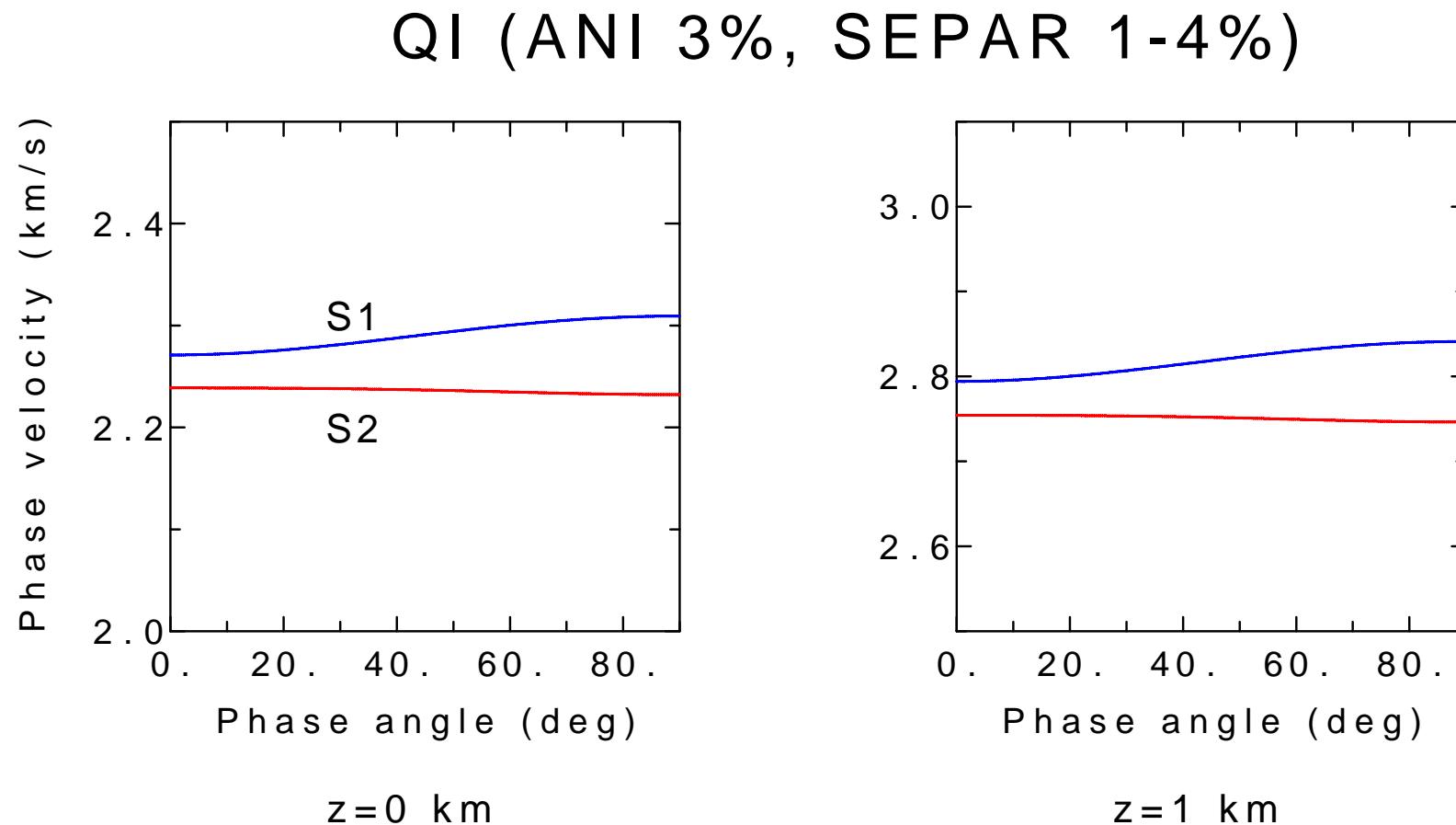
$\xi^{\{0\}}$ - in reference isotropic medium

Numerical examples

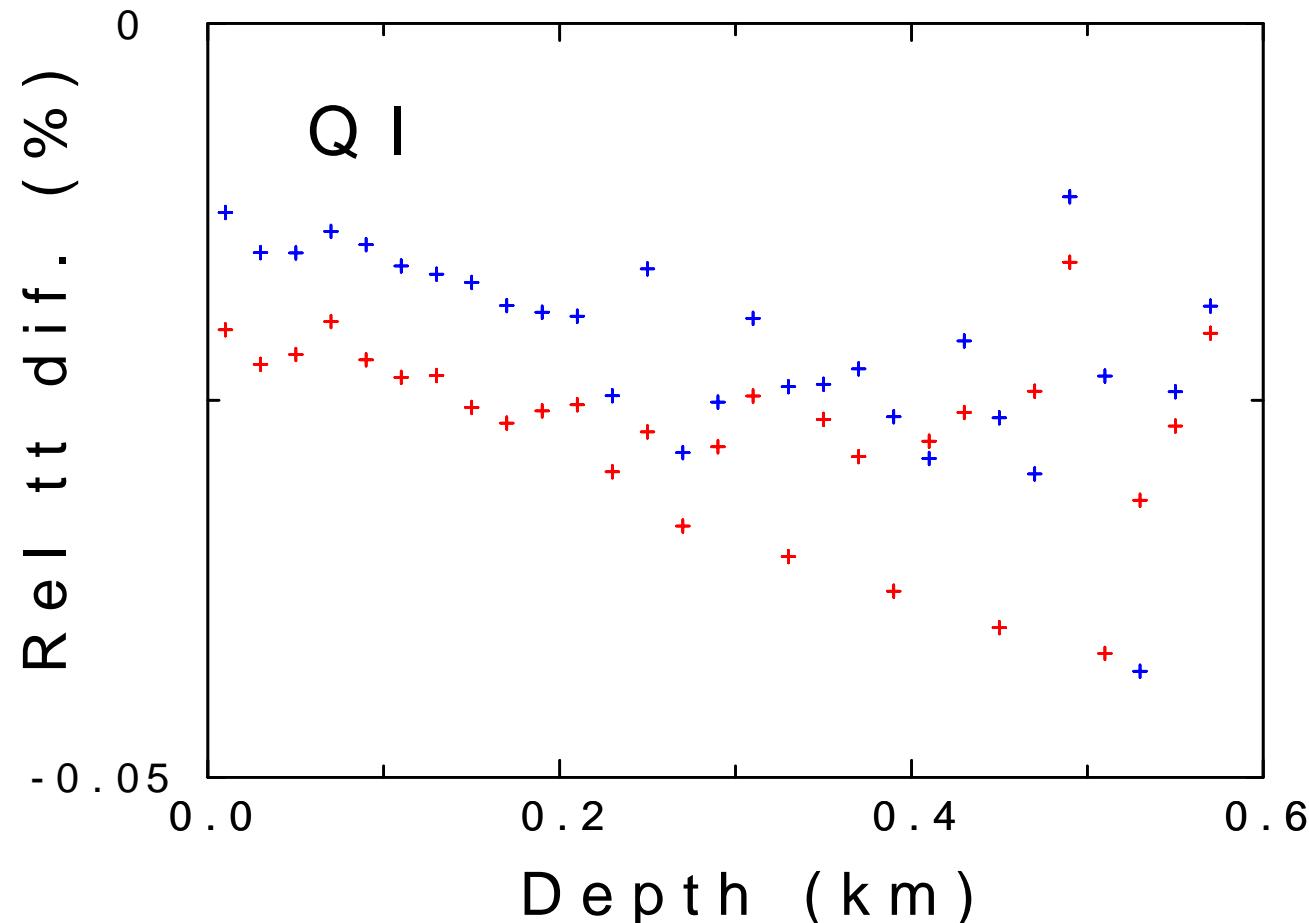


Numerical examples (Klimeš & Bulant, 2004)

HTI rotated by 45 degrees



Numerical examples

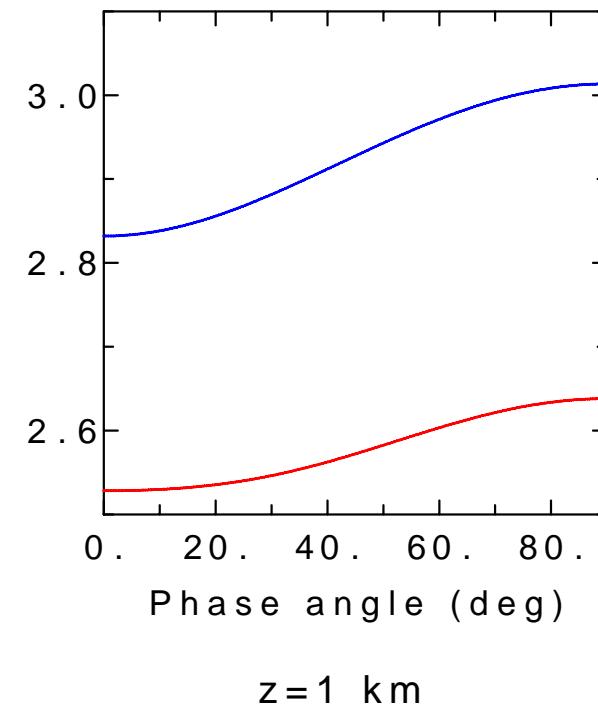
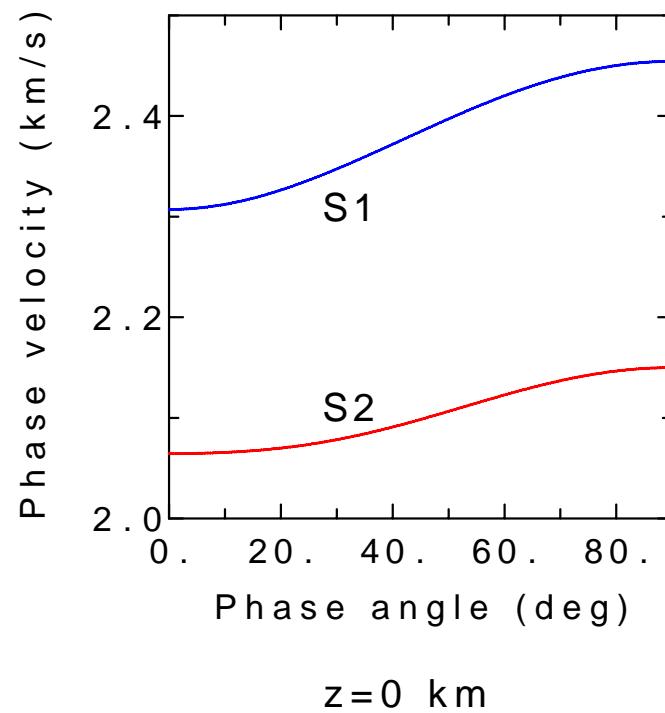


S1 AND S2 WAVES

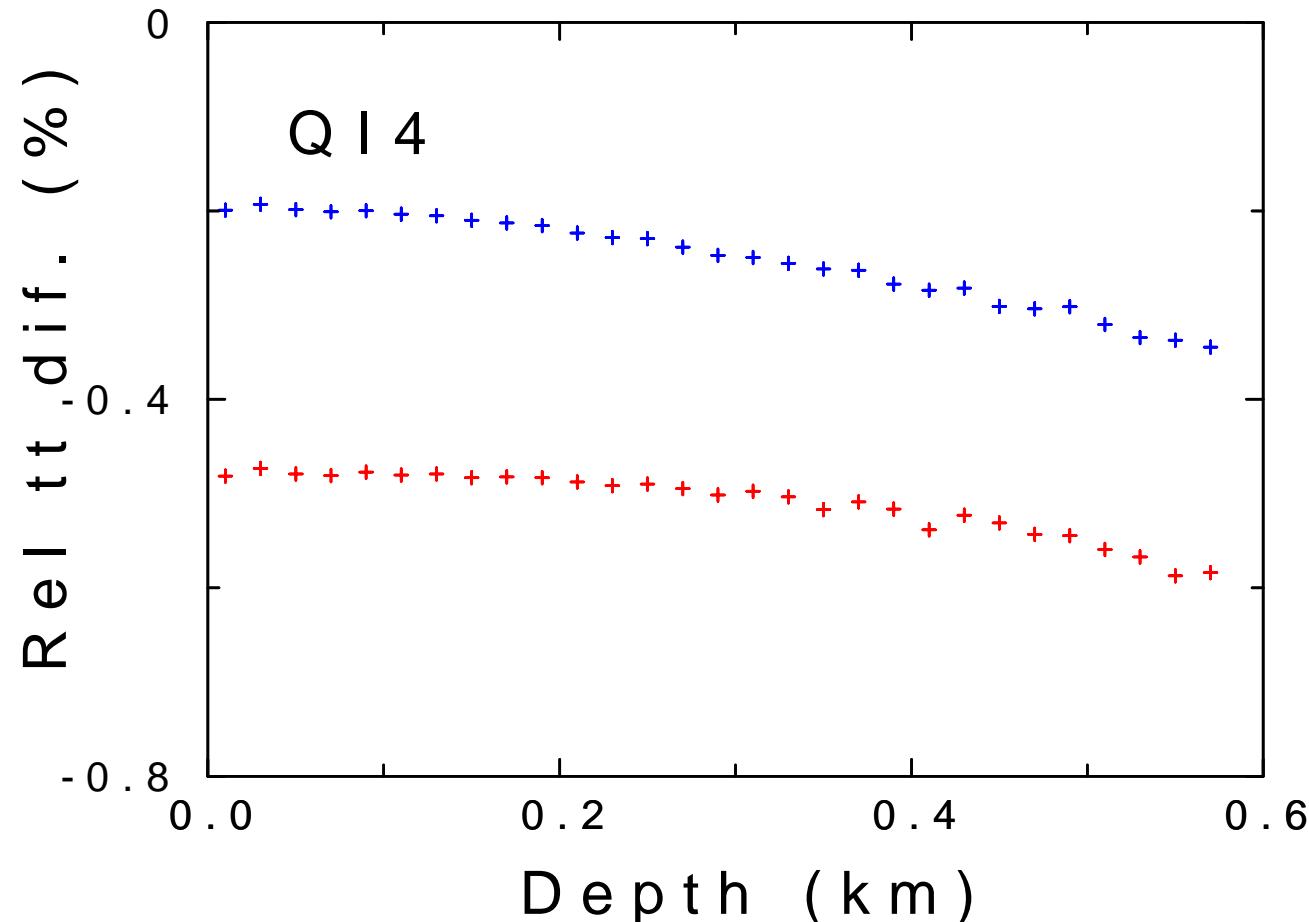
Numerical examples (Klimeš & Bulant, 2004)

HTI rotated by 45 degrees

QI4 (ANI 6%, SEPAR 11-13%)



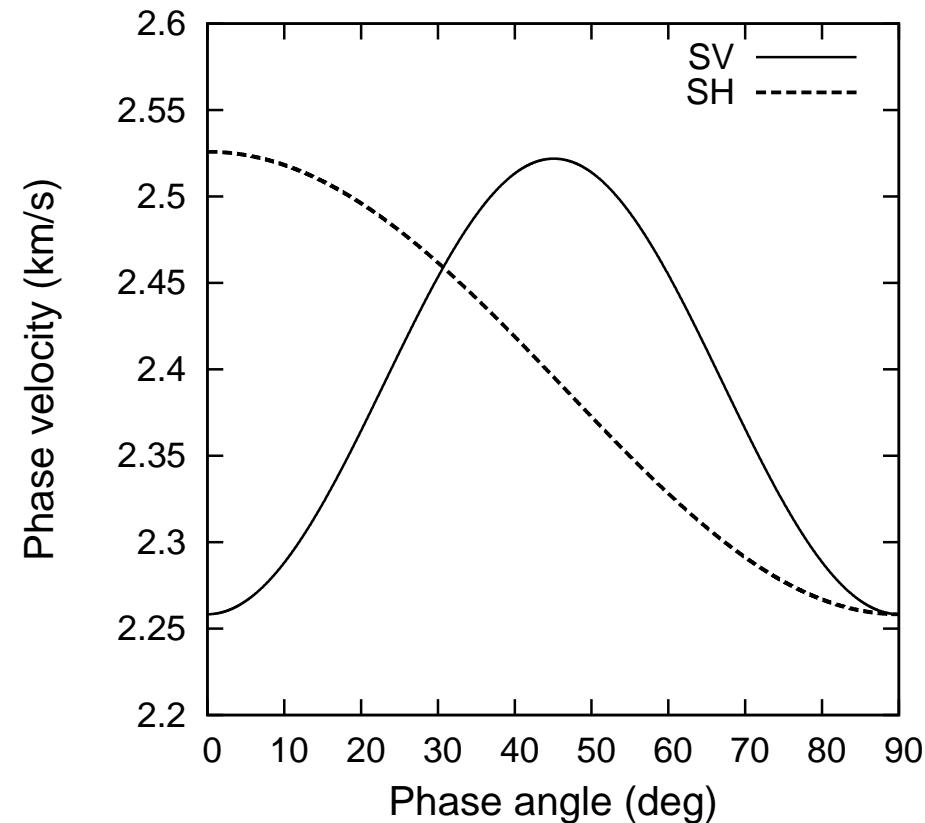
Numerical examples



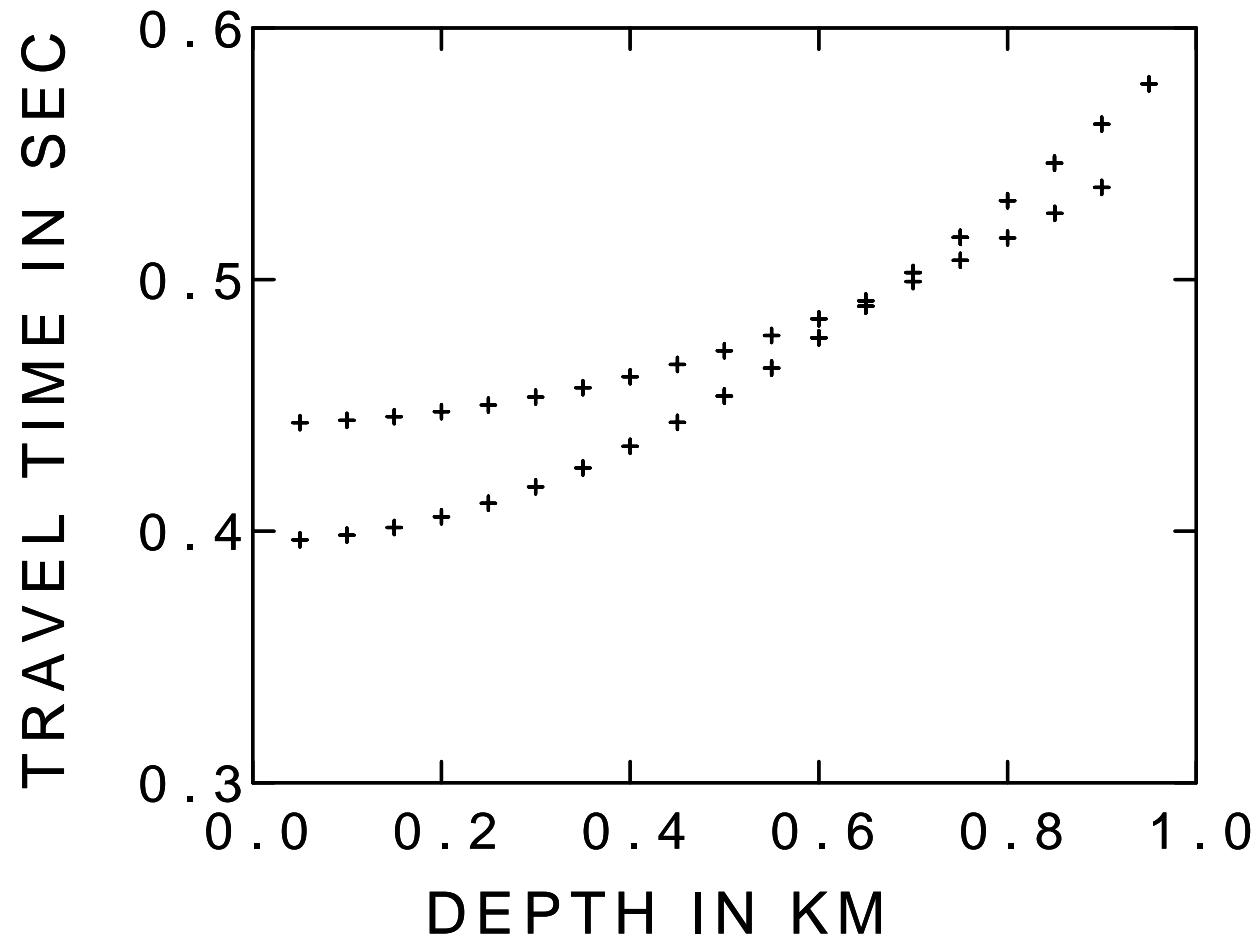
S1 AND S2 WAVES

Numerical examples (Shearer & Chapman, 1989)

VTI: MODEL SC1 (ANI 11%, SEPAR 0-11%)

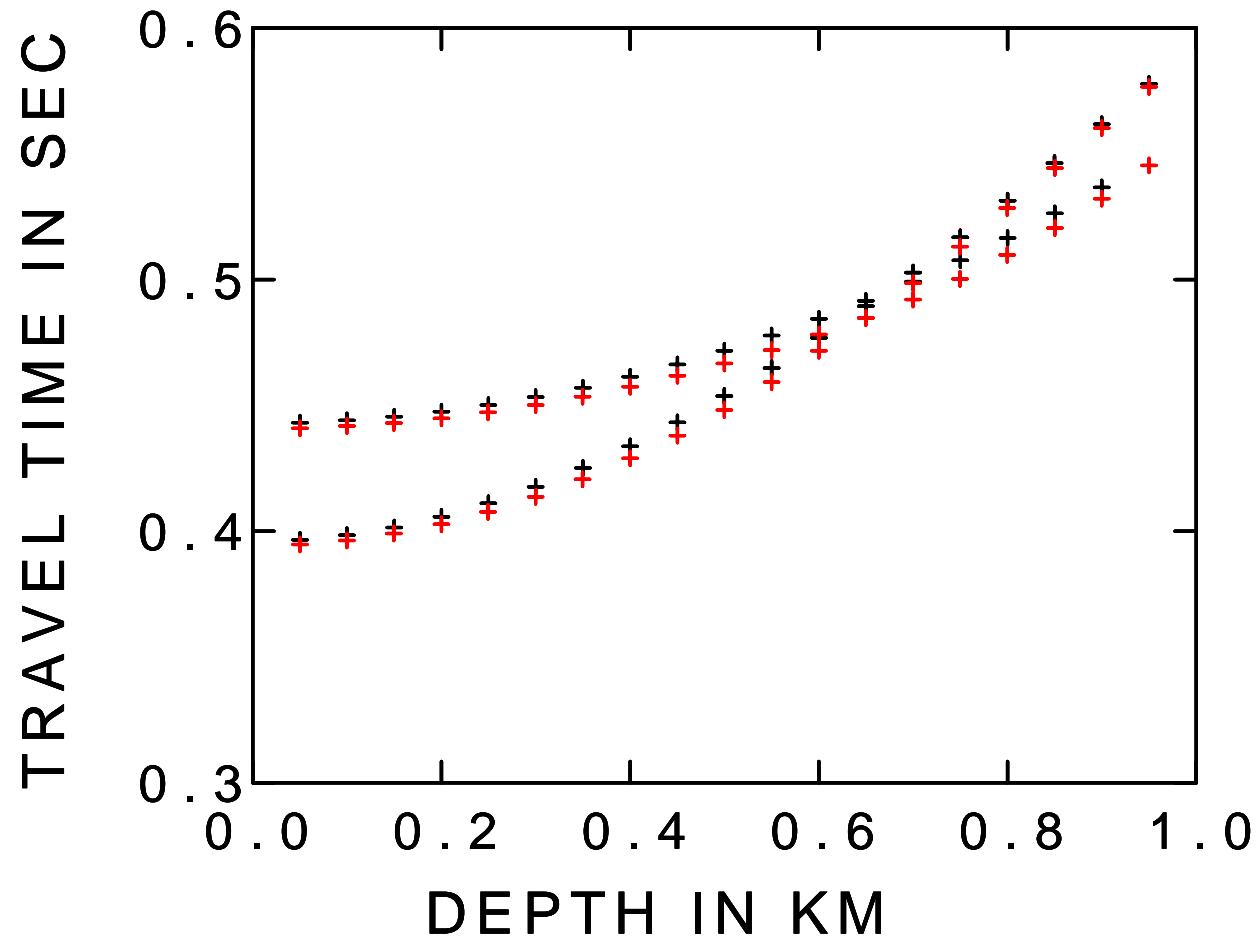


Numerical examples



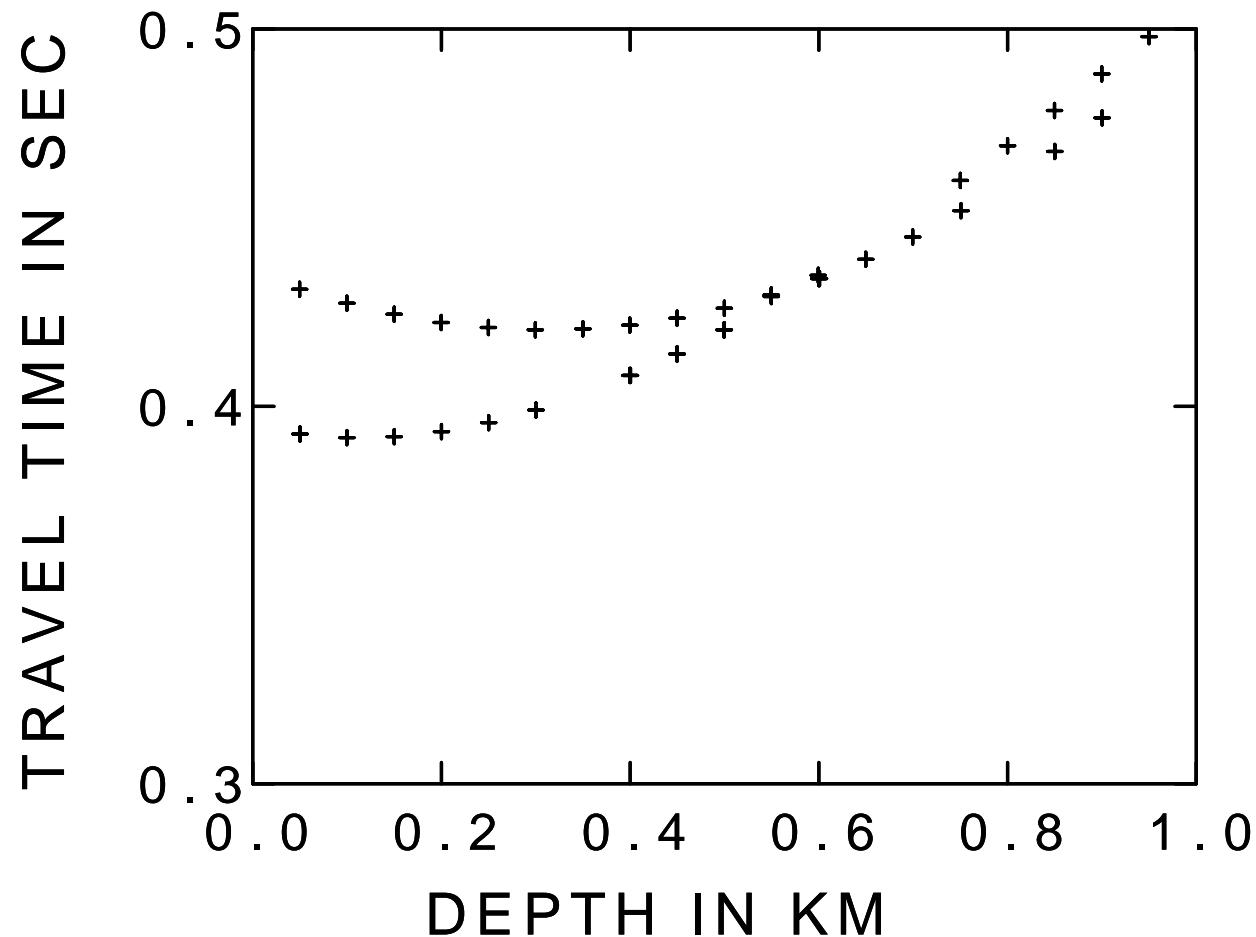
SC1 - HOM., EXACT,

Numerical examples



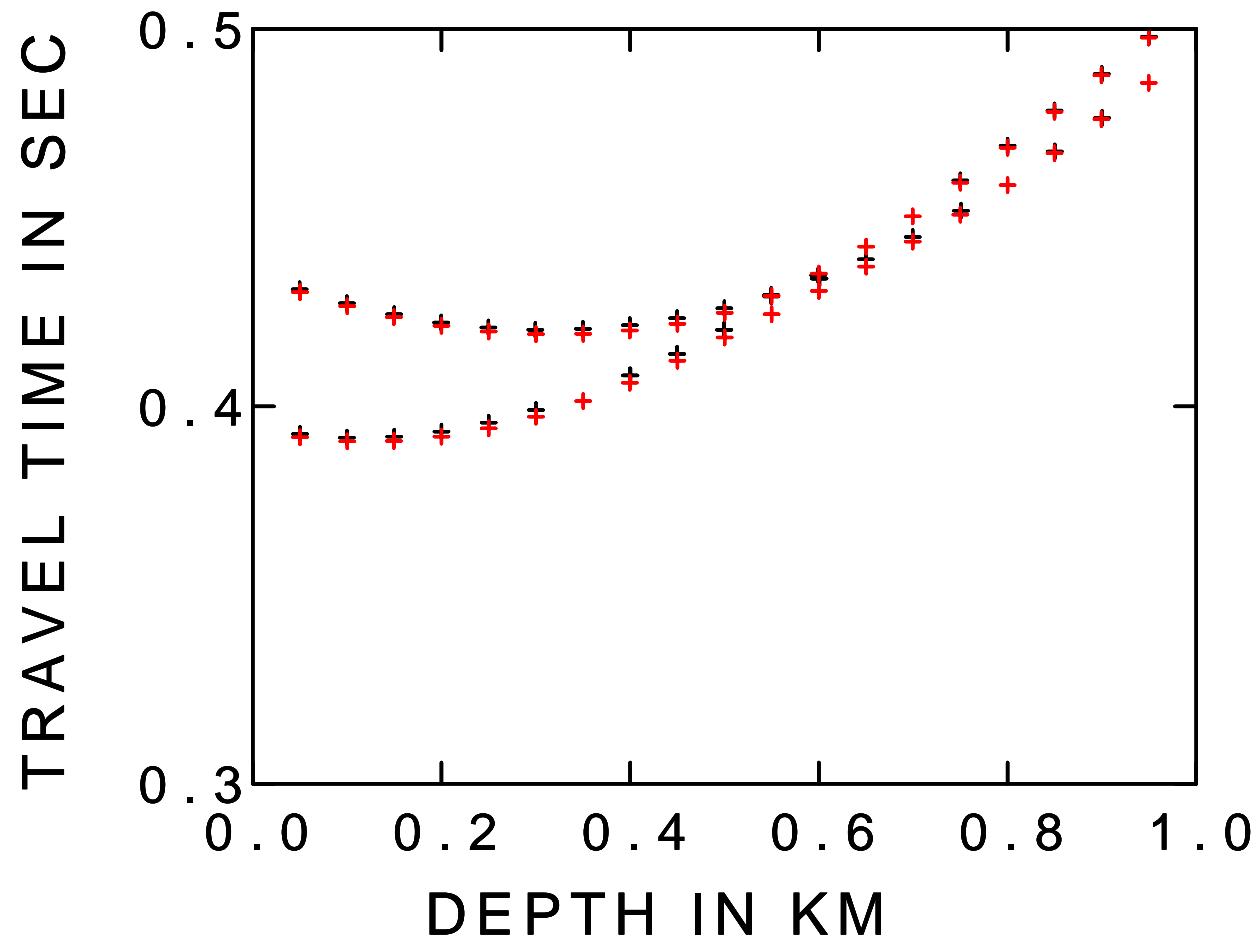
SC1 - HOM., EXACT, APPR.

Numerical examples



SCG1 - INHOM., EXACT,

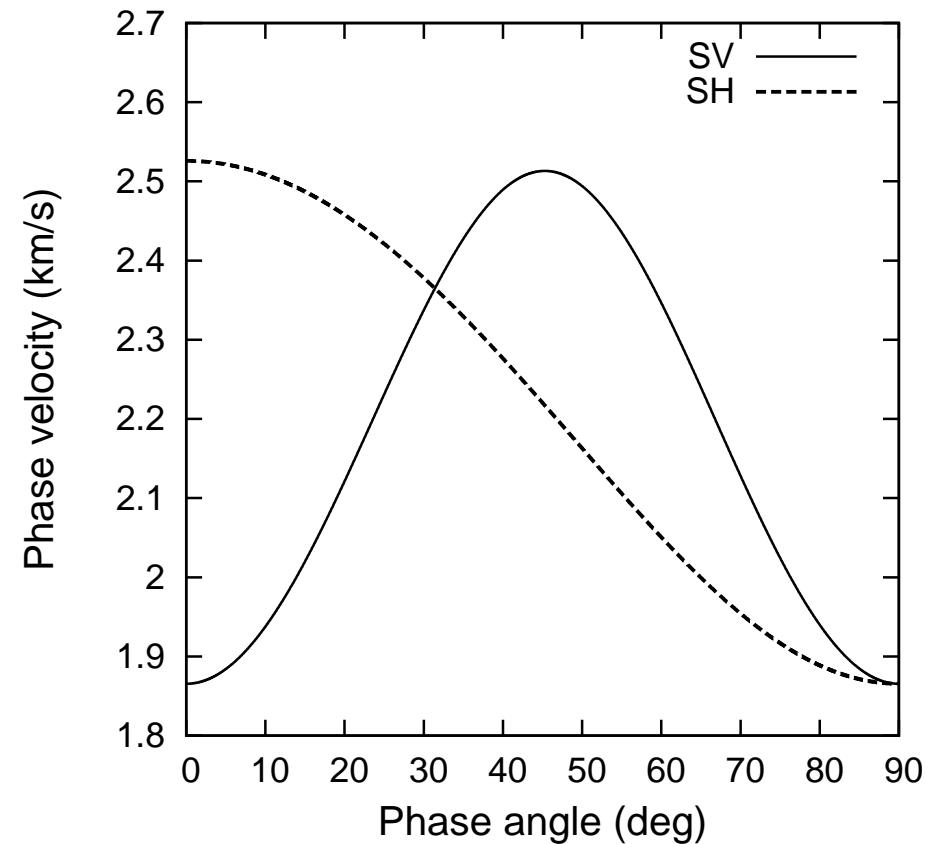
Numerical examples



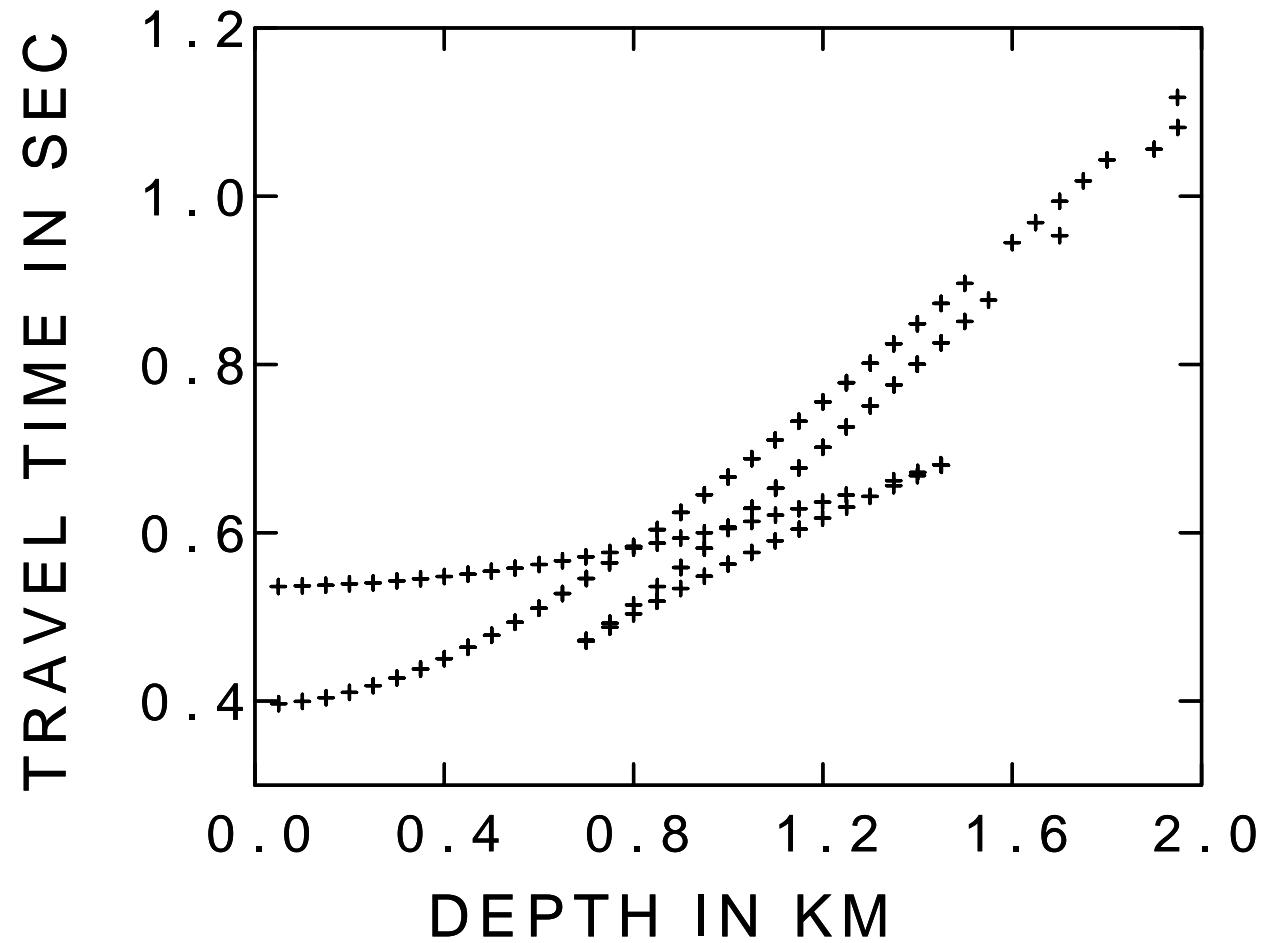
SCG1 - INHOM., EXACT, APPR.

Numerical examples (Shearer & Chapman, 1989)

VTI: MODEL SC4 (ANI 30%, SEPAR 0-30%)

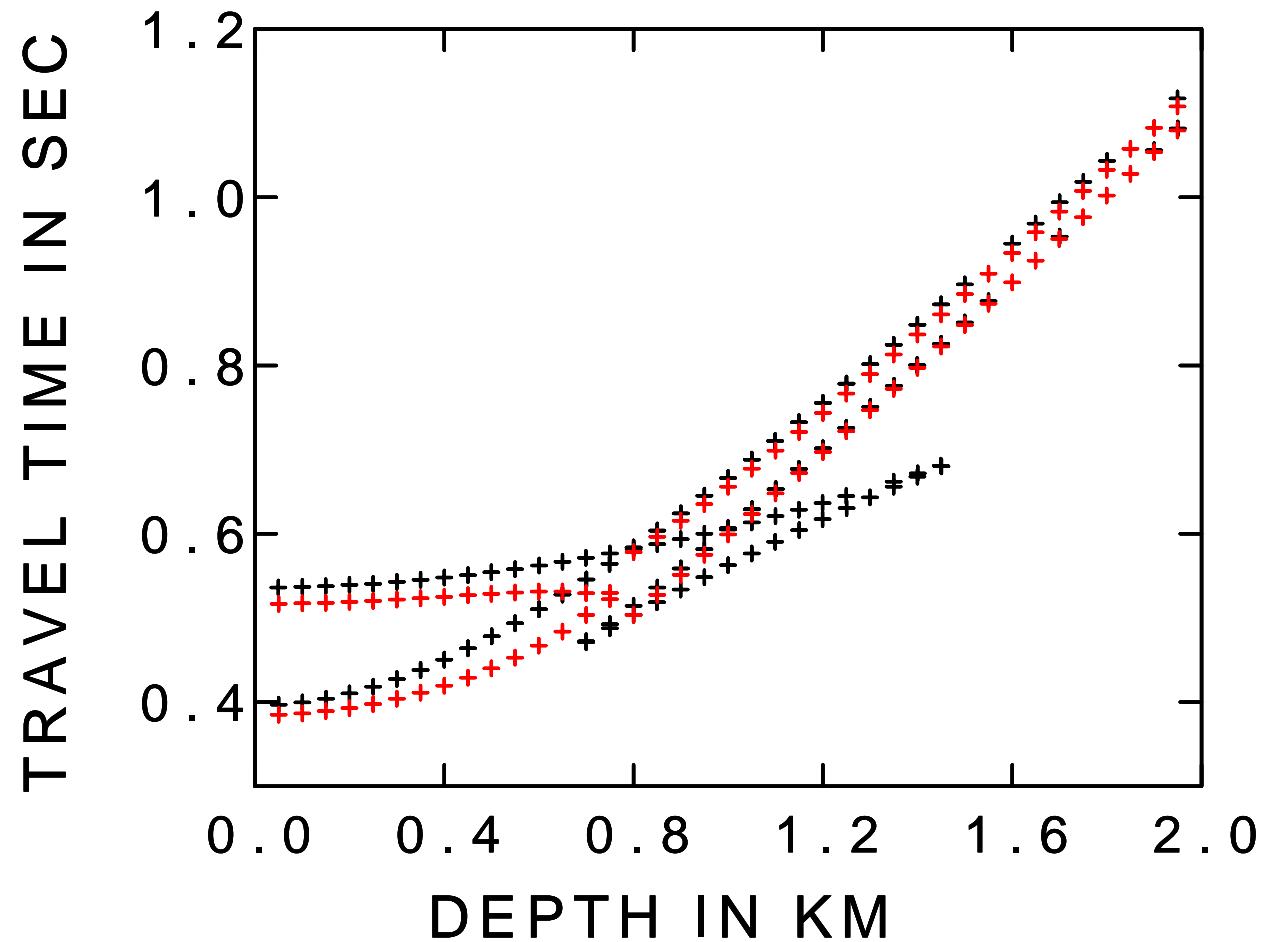


Numerical examples



SC4

Numerical examples



SC4

Conclusions

- applicable to S waves in inhomogeneous isotropic, weakly anisotropic and moderately anisotropic media
- in isotropic media exact, in anisotropic media approximate
- single common S-wave ray necessary for computation of traveltimes of S1 and S2 waves
- common S-wave ray tracing stable, does not collapse anywhere
- computer time savings in computing traveltimes of reflected/transmitted waves
- performs better in inhomogeneous media; smoothes loops in traveltime curves

