

First-arrival traveltimes tomography in anisotropic media using the adjoint-state method

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- Near-surface model parameter estimation
- Initial models for PSDM and FWI
- Traditional methods combine eikonal solver with ray tracing

- Current seismic surveys deploy thousands of sources and receivers
- Fréchet derivative matrix needs extremely large memory
- Solution: reduction in model size or data?

- No explicit computation of Fréchet derivatives
- Cost = Two forward problems
- Gradient computation parallelizable
- Developed only for isotropic media (Leung and Qian, 2006; Taillandier et al., 2009)

Parameterization

- qP-wave traveltimes in VTI medium needs three parameters
- We use v_{nmo} , η , and δ (Stopin and Plessix, 2014)
- δ is weakly resolvable from surface seismics alone (Plessix and Cao, 2011)

- For a single shot, the misfit function is given as

$$J(m) = \frac{1}{2} \int_{\partial\Omega} dr |T^{comp}(m) - T^{obs}|^2$$

- The eikonal equation for VTI media is

$$v_{nmo}^2(1 + 2\eta) \left(\frac{\partial T}{\partial x} \right)^2 + \frac{v_{nmo}^2}{1 + 2\delta} \left(\frac{\partial T}{\partial z} \right)^2 \left(1 - 2\eta v_{nmo}^2 \left(\frac{\partial T}{\partial x} \right)^2 \right) = 1$$

$$T(s) = 0$$

- The adjoint variable λ satisfies

$$\nabla \cdot (L\lambda) = 0$$

with the boundary condition

$$(\mathbf{n} \cdot L)\lambda = T^{obs} - T^{comp}$$

where

$$L = \begin{bmatrix} \left(v_{nmo}^2 (1 + 2\eta) - 2\eta v_{nmo}^2 v_0^2 \left(\frac{\partial T}{\partial z} \right)^2 \right) \left(\frac{\partial T}{\partial x} \right) \\ \left(v_0^2 - 2\eta v_{nmo}^2 v_0^2 \left(\frac{\partial T}{\partial x} \right)^2 \right) \left(\frac{\partial T}{\partial z} \right) \end{bmatrix}$$

- The gradient of the misfit function is given as:

$$\frac{\partial J}{\partial v_{nmo}} = \int_{\Omega} v_{nmo} \left((1 + 2\eta) \left(\frac{\partial T}{\partial x} \right)^2 + \frac{1}{1 + 2\delta} \left(\frac{\partial T}{\partial z} \right)^2 \right) \lambda dx$$

$$\frac{\partial J}{\partial \eta} = \int_{\Omega} v_{nmo}^2 \left(\frac{\partial T}{\partial x} \right)^2 \left(1 - \frac{v_{nmo}^2}{1 + 2\delta} \left(\frac{\partial T}{\partial z} \right)^2 \right) \lambda dx$$

- The model parameters can be updated using:

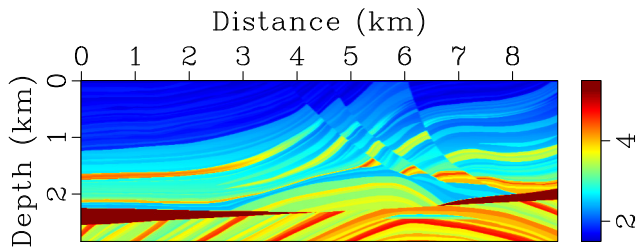
$$m^{k+1} = m^k - \alpha^k \nabla J(m^k)$$

Implementation Details

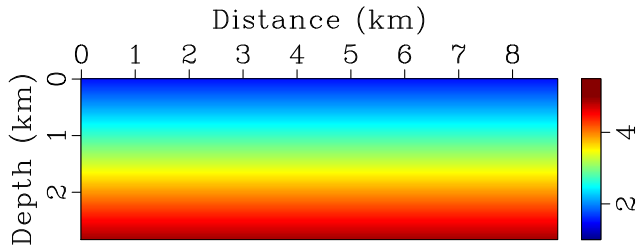
Forward and adjoint solvers

- Eikonal equation: (Waheed et al., 2015)
- FS based solver for the adjoint-state equation
- Solving them gives us the adjoint-state variable λ

Smoothing the gradient

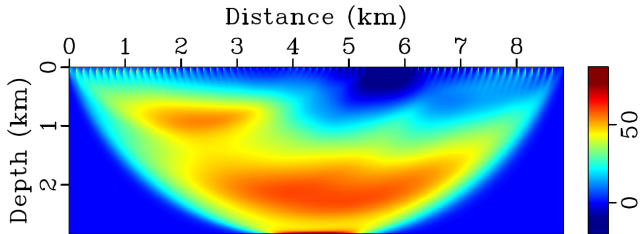


True



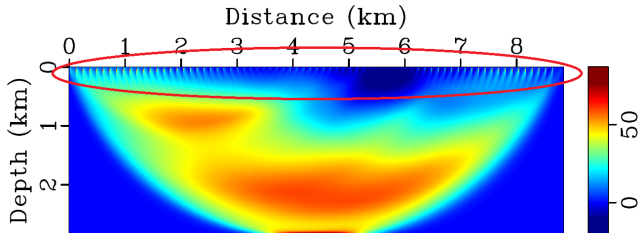
Initial

Smoothing the gradient



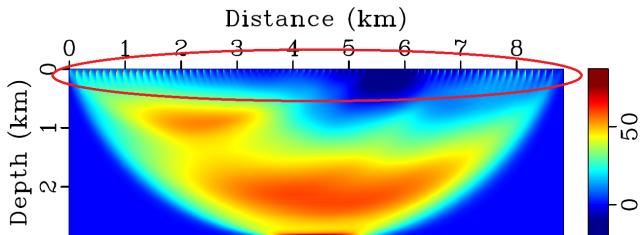
Before Smoothing

Smoothing the gradient

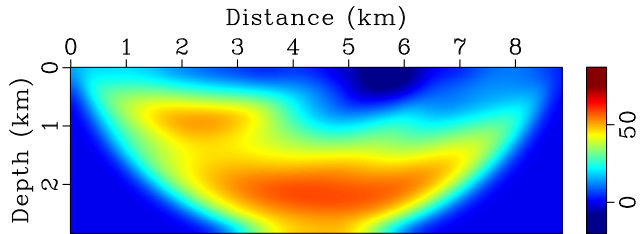


Before Smoothing

Smoothing the gradient



Before Smoothing



After Smoothing

Smoothing the gradient

- **Four stage adaptive smoothing**
- **Begins: 50 grid points window**
- **Ends: distance between two consecutive sources**

- Optimization algorithm: Nonlinear Conjugate Gradient

1. Compute $\beta^k = \max(0, \beta^{PR})$, where:

$$\beta^{PR} = \frac{(\nabla J^k)^T (\nabla J^k - \nabla J^{k-1})}{(\nabla J^{k-1})^T (\nabla J^{k-1})}$$

Inversion setup

- Optimization algorithm: Nonlinear Conjugate Gradient

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$$s^k = -\nabla J^k + \beta^k s^{k-1}$$

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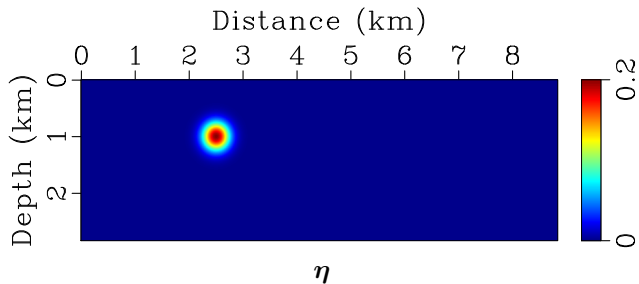
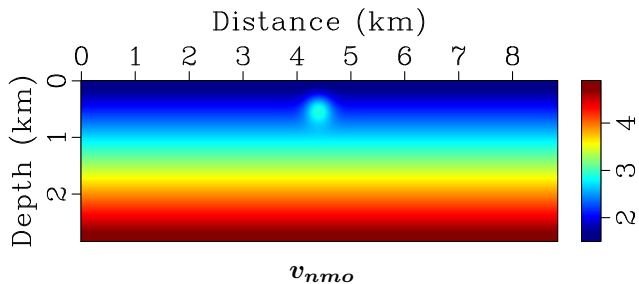
4. Update the model:

$$m^{k+1} = m^k + \alpha^k s^k$$

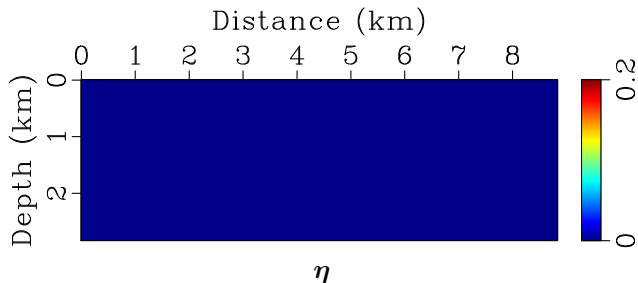
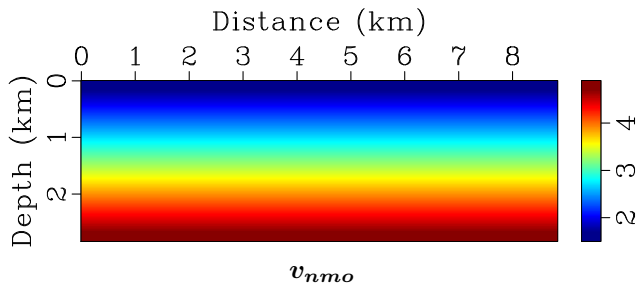
- **Line search:** Satisfies strong Wolfe criteria
- **Gradient** computed separately for each shot
- **Parallelization:** OpenMP

Challenge: Multiparameter Inversion

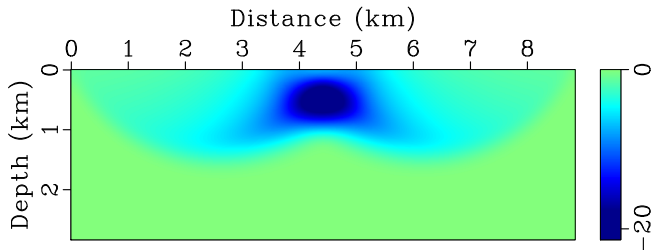
Multiparameter Inversion: True Model



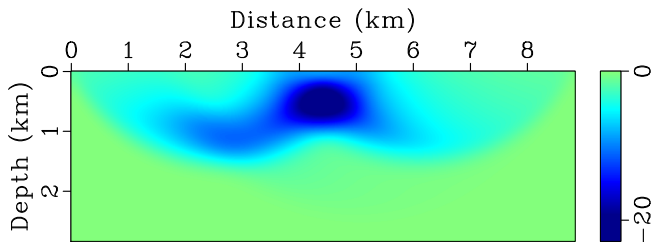
Multiparameter Inversion: Initial Model



Multiparameter Inversion: Gradient

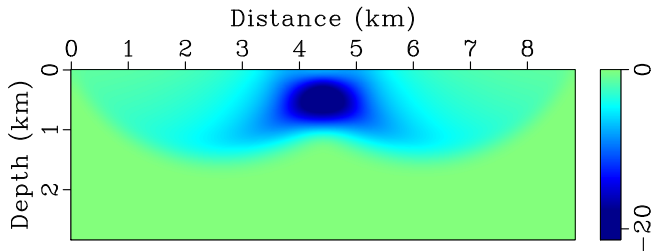


Isotropic

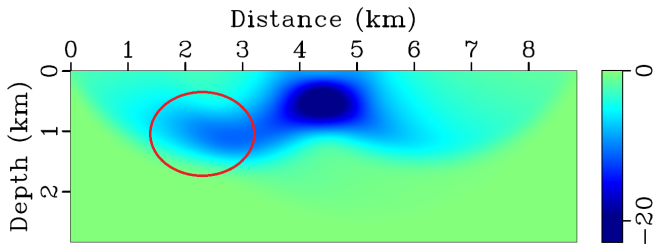


Anisotropic

Multiparameter Inversion: Gradient



Isotropic



Anisotropic

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1. Simultaneous: v_{nmo} and $v_h (v_h = v_{nmo} \sqrt{1 + 2\eta})$

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2. Hybrid: Stage 1 - v_{nmo}
Stage 2 - v_{nmo} and η
3. Sequential: Stage 1 - v_{nmo}
Stage 2 - η

Multiparameter Inversion

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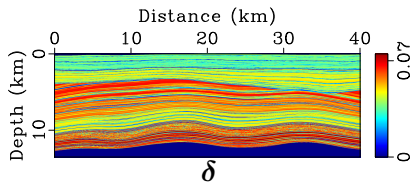
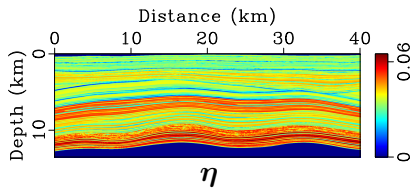
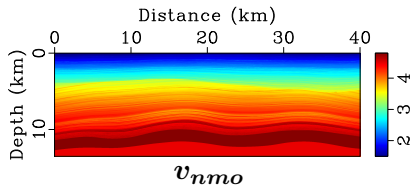
2. **Hybrid:** Stage 1 - v_{nmo}
Stage 2 - v_{nmo} and η

3. **Sequential:** Stage 1 - v_{nmo}
Stage 2 - η

- **When to switch from Stage 1 to Stage 2?**

Numerical Tests

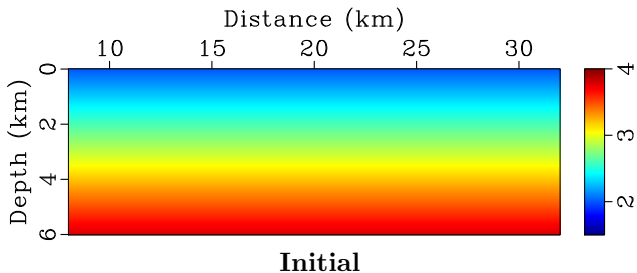
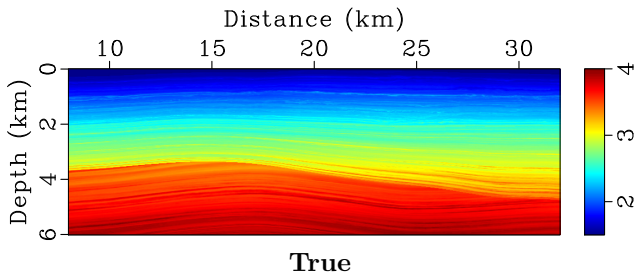
VTI SEAM Model



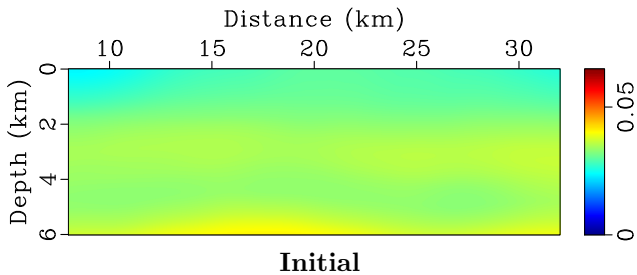
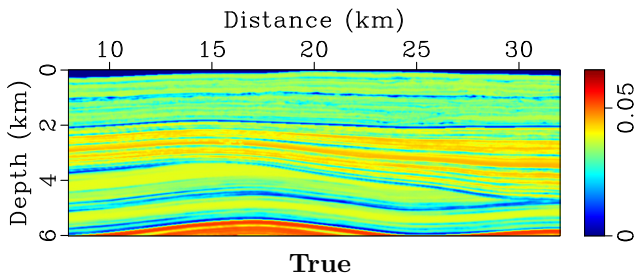
VTI SEAM Model Test

- $nx = 2001, nz = 676$
- $dx = dz = 20$ m
- Number of shots = 101
- Receiver spacing = 20 m

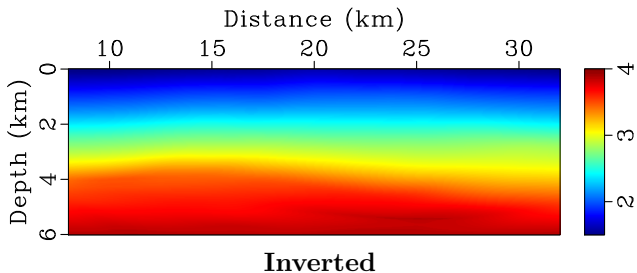
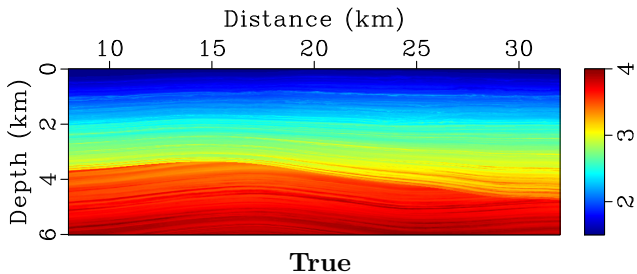
NMO Velocity



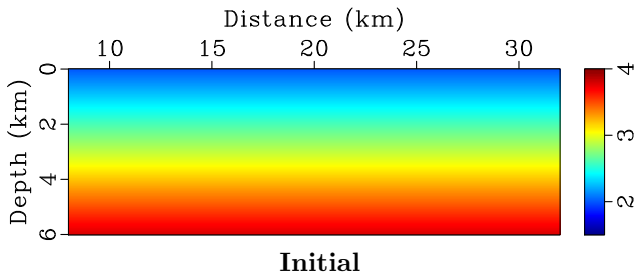
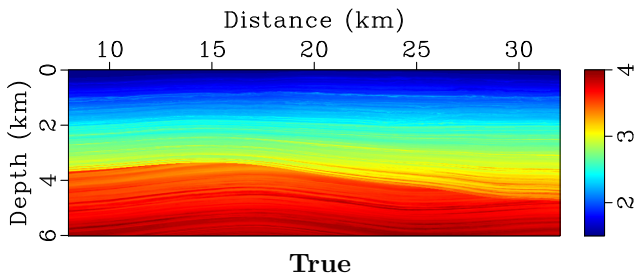
η parameter



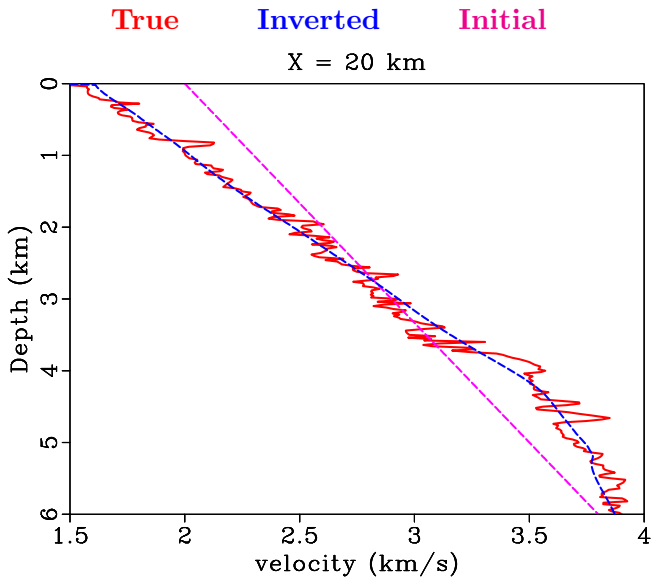
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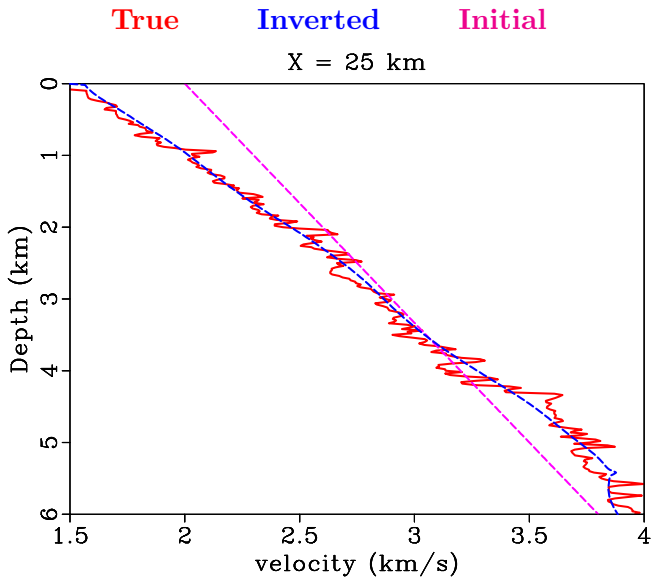
NMO Velocity



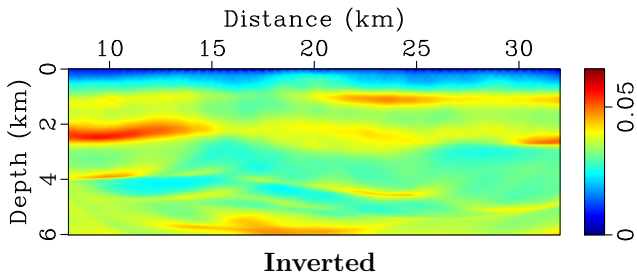
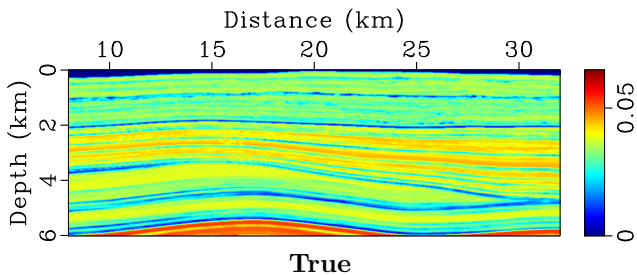
NMO Velocity



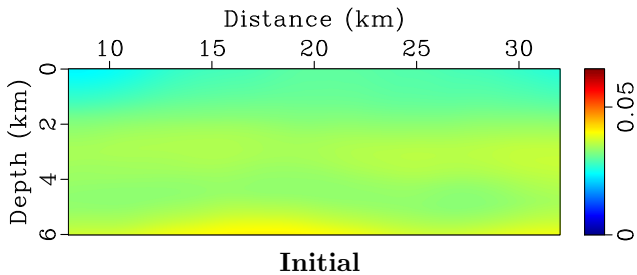
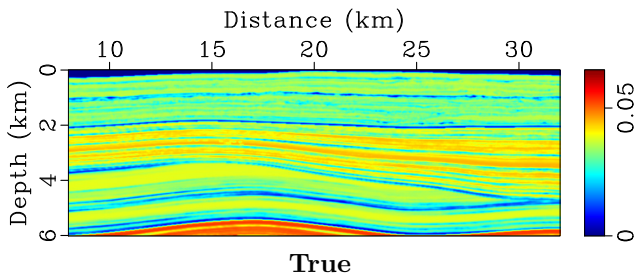
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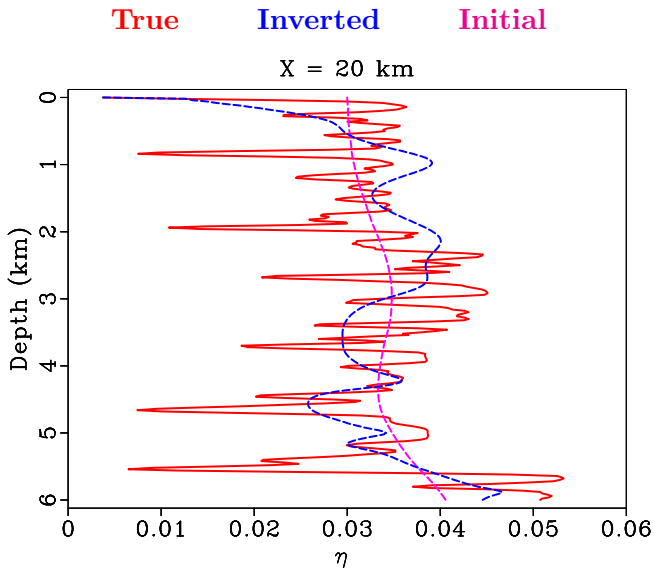
η parameter



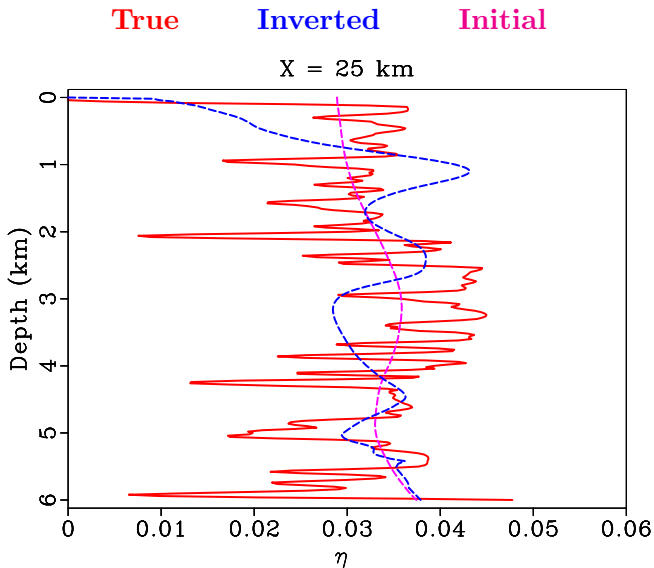
η parameter



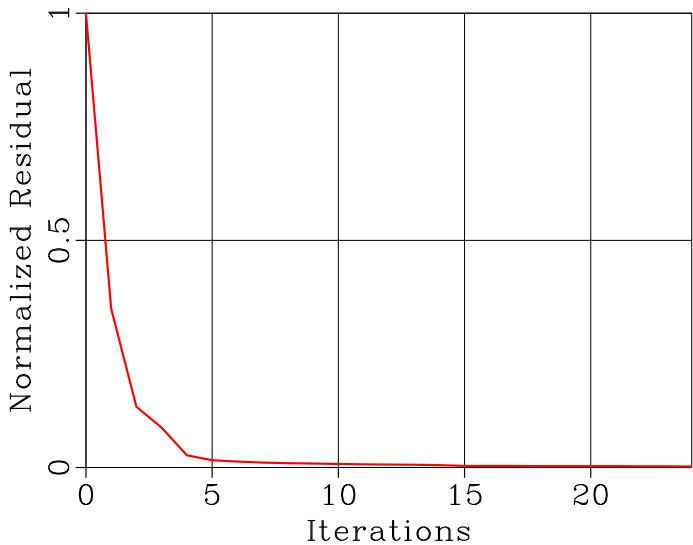
η parameter



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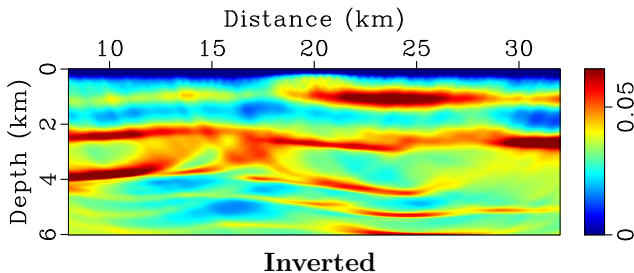
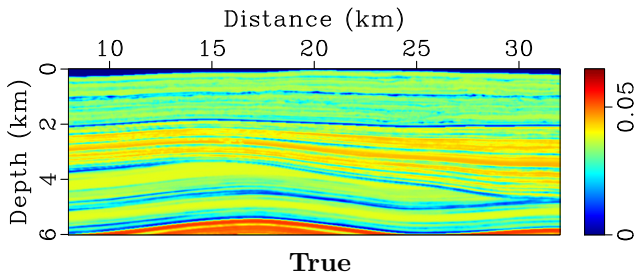
Normalized Residual



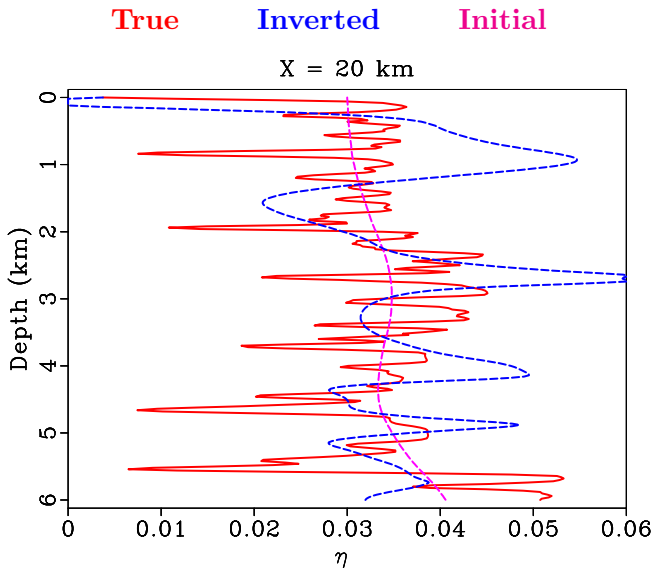
Switching between parameters

- **Stage 1:** reduce the residual up to 10% of its initial value
- **Stage 2:** force the remaining residual into η
- **Assumption:** knowledge of upper bound on η

Switching between parameters



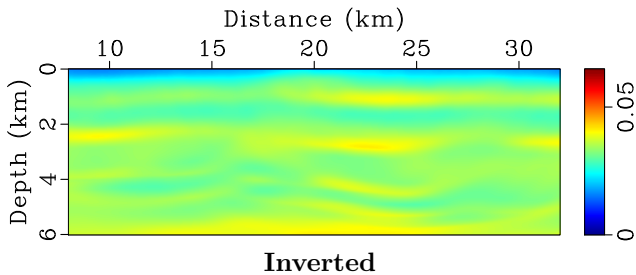
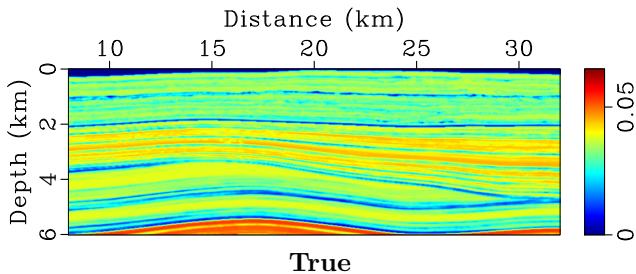
Switching between parameters



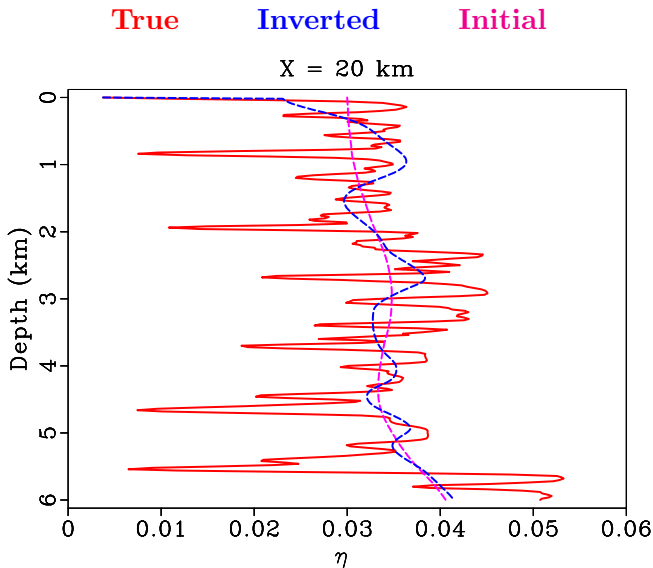
Switching between parameters

- **Stage 1:** reduce the residual up to 5% of its initial value
- **Stage 2:** force the remaining residual into η
- **Assumption:** knowledge of upper bound on η

Switching between parameters



Switching between parameters



Inversion for δ

- **Additional source of information, such as receivers in borehole**

Inversion for δ

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- The adjoint variable λ satisfies

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Inversion for δ

- Additional source of information, such as receivers in borehole
- The adjoint variable λ satisfies

$$\nabla \cdot (L\lambda) = 0$$

with the boundary condition

$$(\mathbf{n} \cdot L)\lambda = T^{obs} - T^{comp}$$

- For receivers inside the medium, λ satisfies

$$\nabla \cdot (L\lambda) = T^{obs} - T^{comp}$$

- **FAT tomography algorithm using the adjoint-state method**
- **Candidate for first round on board model building**
- **Multi-parameter inversion**

- Extendable to lower anisotropic symmetries
- Need a strategy to decouple additional parameters
- Borehole measurements can help resolve δ

Acknowledgments

- Schlumberger for financial support and permission to share results

- Marvin Decker, Xin Cheng, Marta Woodward, James Rickett, Chris Chapman, and Michael Williams for useful discussions

Strong Wolfe Criteria

- Sufficient decrease condition:

$$f(x + \alpha p) \leq f(x) + c_1 \alpha_k \nabla f(x) \cdot p$$

- Curvature condition:

$$|\nabla f(x + \alpha p) \cdot p| \leq c_2 |\nabla f(x) \cdot p|$$